JIAYI WU

jiayi-wu-leo.github.io | 5302 Davis Point Ln | Greenbelt, MD 20770 | (352)709-0593 | jiayiwu@umd.edu

EDUCATION

University of Maryland, College Park		College Park, MD, US
Ph.D in Computer Science	GPA:3.825/4.000	Aug. 2023- Present
• Advisor: Prof. Yiannis Aloimonos		
University of Florida		Gainesville, FL, US
M.S. (Thesis) in Electrical and Computer Engineering	GPA:3.83/4.00	Aug. 2021- May. 2023
• Advisor: Prof. Md Jahidul Islam		
Zhejiang Sci-Tech University (ZSTU)		Hangzhou, CN
B.E. in Mechatronic Engineering	GPA: 86/100	Sept. 2017- Jun. 2021

• 2021 Outstanding Graduate, Zhejiang Sci-Tech University

PREPRINTS

[1] **Wu, Jiayi**, Xiaomin Lin, Botao He, Cornelia Fermuller, and Yiannis Aloimonos. "ViewActive: Active viewpoint optimization from a single image." arXiv preprint arXiv:2409.09997 (2024). In review at the ICRA 2025 [Arxiv]

PUBLICATIONS AND PATENTS

- [1] Xiong, Tianyi*, Wu, Jiayi*, He, Botao, Fermüller, Cornelia, Aloimonos, Yiannis, Huang, Heng, and A. Metzler, Christopher. "Event3DGS: Event-Based 3D Gaussian Splatting for High-Speed Robot Egomotion." Conference on Robot Learning (CoRL 2024) [Pre-print]
- [2] Wu, Jiayi*, Lin, Xiaomin*, Negahdaripour, Shahriar, Fermüller, Cornelia, and Aloimonos, Yiannis.

 "MARVIS: Motion & Geometry Aware Real and Virtual Image Segmentation." IEEE/RSJ International

 Conference on Intelligent Robots and Systems (IROS 2024) [Pre-print]
- [3] Wu, Jiayi, Yu, Boxiao, Islam, Md Jahidul. "3D Reconstruction of Underwater Scenes using Nonlinear Domain Projection." Best Paper Award at the IEEE Conference on Artificial Intelligence (IEEE CAI 2023) [IEEE Xplore] [Poster] [Demo]
- [4] Yu, Boxiao, **Wu, Jiayi**, Islam, Md Jahidul. "UDepth: Fast Monocular Depth Estimation for Visually-guided Underwater Robots." IEEE International Conference on Robotics and Automation (ICRA 2023)

 [IEEE Xplore] [Code] [Demo]
- [5] Wu, Jiayi. "Low-Cost Depth Estimation and 3D Reconstruction in Scattering Medium." Master's Thesis. 2023 [UFDC]
- [6] A. K. Roberts, J. Wu, A. Monsivais-Huertero, J. Judge, R. C. Moore and K. Sarabandi, "Microwave Backscatter Phenomenology of Corn Fields at L-Band Using a Full-Wave Electromagnetic Solver."

 IEEE Transactions on Geoscience and Remote Sensing (IEEE TGRS) [IEEE Xplore]

- [7] A. Kaleo Roberts, Kamal Sarabandi, Jasmeet Judge, Alejandro Monsivais-Huertero, **Jiayi Wu**.

 "Validation of a Full-wave Backscatter Model for Corn Fields using Measurements from a Ground-based Scatterometer." IEEE International Geoscience and Remote Sensing Symposium (IGARSS 2023)
- [8] Wu, Jiayi. "Unmanned automobile automatic charging system and charging docking method." A National Invention Patent has been granted. [CN113511087A]
- [9] Wu, Jiayi. "Stilt type deformation wheel." A Utility Model Patent has been granted. [CN212400777U]

EXPERIENCES

Ph.D. Research in PRG Lab

University of Maryland, College Park, MD, US

Teaching Assistant & Research Assistant

Aug. 2023- Present

- Proposed ViewActive, a novel framework for active viewpoint optimization that mimics human-like spatial reasoning to enhance robotic perception. (submitted to ICRA 2025)
- Proposed Event3DGS, an event-based 3D Gaussian Splatting method that achieves state-of-the-art reconstruction quality and significantly accelerates training and rendering. (accepted by CoRL 2024)
- Presented MARVIS, a cutting-edge solution for real-virtual image segmentation near water surfaces, effectively leveraging synthetic data and domain-invariant features. (accepted by IROS 2024)

Underwater 3D Vision Research Intern in RoboPI Lab

University of Florida, Gainesville, FL, US

Master's thesis

Jan. 2022- Jun. 2023

- Designed an underwater compatible SfM pipeline that enhances the robustness of terrestrial SfM to scattering medium environments. One paper won *Best Paper Award at IEEE CAI 2023*.
- Formulated a robust and efficient end-to-end model named UDepth, for fast monocular depth estimation by incorporating underwater domain knowledge into its supervised learning pipeline. One paper has been *accepted by ICRA 2023*.

Digital Audio and Video Algorithm Engineer in Vobile

Vobile, Santa Clara, CA, US

R&D Summer Internship (supervised by Dr. Jian Zhao, CTO of Vobile, Inc.)

May. 2022- Aug. 2022

- Developed and implemented a learning-based video retrieval system based on global feature and local feature fusion. And also wrote the user manual and targeted model performance optimization guidelines document of the system.
- Conducted a number of qualitative phase-shift auditory tests and found a relationship between the phase-shift cases and the psychoacoustic model. Upgraded the audio fingerprint encoding algorithm based on the classic psychoacoustic model. The upgraded algorithm can encode not only the sound pressure level of the audio fingerprint but also the threshold of its phase shift. (Implemented in C and MATLAB)

Python Toolkit Development in Remote Sensing Lab

University of Florida, Gainesville, FL, US

Graduate Student Assistant

Jan. 2022- Jan. 2023

- Completed 3D model generation code packages for corn and soybean plants, the packages can load data from the database and automatically generate 3D models of plants in large batches.
- Toolkit updates and optimizations for speed and data irregularities.

• A paper titled " Validation of a Full-wave Backscatter Model for Corn Fields using Measurements from a Ground-based Scatterometer " has been accepted by IGARSS 2023.

HONORS & AWARDS

SCHOLARSHIPS	
UMIACS Fellowship	2024
UF Herbert Wertheim College of Engineering Engineering Achieve Award	
Zhejiang Government Scholarship	2020 2018
First Class School Financial Aid for Overseas Exchange Program	2019
COMPETITIONS	
Individual first prize in the National University Graduate Design Competition	
(Only two people won this award nationwide)	06/2021
Provincial First Prize of National 3D Digital Innovative Design Competition	
Second Prize of National 3dds Competition Classic	
Third Prize of The 16 th Zhejiang Province Mechanical Design Competition for College Student	
Third Prize of The Challenge Cup Extracurricular Academic Works Competition	
Second Prize of <i>Internet</i> + School Competition	

PROFESSIONAL SKILLS

PROGRAMMING

• Proficient: C, Python (TensorFlow, PyTorch, OpenCV, Open3d, etc), MATLAB

• Familiar: C++

SOFTWARES

• Proficient: MATLAB, ROS, SolidWorks, Ansys, SpaceClaim (by code), Altium Designer

• Familiar: Verilog, Catia, Labview

ACADEMIC SERVICES

- Reviewer for NeurIPS 2024.
- Reviewer for ICRA 2023 | 2024.
- Reviewer for IROS 2023 | 2024.
- Reviewer for IEEE JOE.